

CBCS SCHEME

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15ME73

Seventh Semester B.E. Degree Examination, Jan./Feb. 2023 Control Engineering

Time: 3 hrs.

Max. Marks: 80

Note: Answer any FIVE full questions, choosing ONE full question from each module.

Module-1

- 1 a. Compare open loop and closed loop control system with example. (08 Marks)
- b. Explain basic structure of a feedback control system with a suitable example and block diagram. (08 Marks)

OR

- 2 a. Explain the ideal requirements of control system with example. (06 Marks)
- b. What is controller? Compare PI, PD and PID controllers, with block diagram and relevant characteristics equation. (10 Marks)

Module-2

- 3 a. Determine system equation of the system shown in Fig.Q.3(a) and draw force-voltage analogy. (08 Marks)

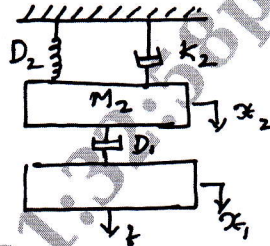


Fig.Q.3(a)

- b. A thermometer is dipped in a vessel containing liquid at a constant temperature of θ_1 . thermometer has a thermal capacitance for storing heat as C and thermal resistance to limit heat flow as R . If the temperature indicated by thermometer is θ_r , obtain the transfer function of the system. (08 Marks)

OR

- 4 a. Determine the transfer function of the system by block diagram reduction technique. (08 Marks)

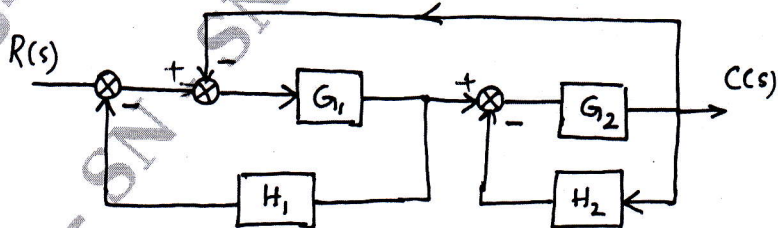


Fig.Q.4(a)

Important Note : 1. On completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages.
2. Any revealing of identification, appeal to evaluator and /or equations written eg, 42+8 = 50, will be treated as malpractice.

- b. Determine the transfer function of the system by Mason's gain formula. (08 Marks)

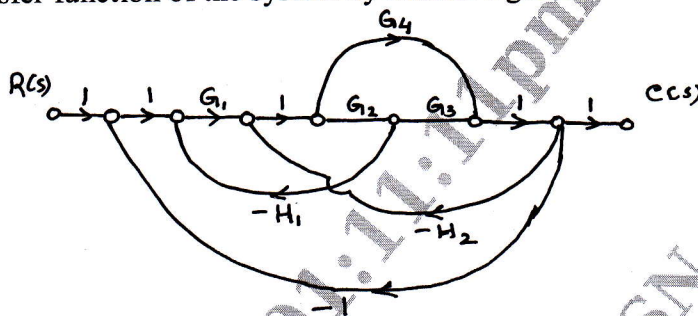


Fig.Q.4(b)

Module-3

- 5 a. Examine the stability of the system represented by the characteristic equation $2s^4 + 10s^3 + 2s^2 + 5s + k = 0$. Using RH criterion. Suggest the range of K for the system to be stable. (08 Marks)
- b. Derive the governing expression for the first order system subjected to unit step response. (06 Marks)
- c. Explain the transient response characteristics of a control system to a unit step input. (02 Marks)

OR

- 6 A negative feedback control system is characterized by $G(s)H(s) = \frac{K}{s(s+1)(s+2)(s+3)}$. Generate the root locus plot for values of K ranging from 0 to ∞ . (16 Marks)

Module-4

- 7 Sketch the Bode plot for a unit feedback system with $G(S) = \frac{242(S+5)}{S(S+1)(S^2+5S+12)}$ and comment on stability. (16 Marks)

OR

- 8 Draw the Nyquist plot for a system with $G(S)H(S) = \frac{K}{S(S+1)(S+2)}$ and find the range of values of K for stability. (16 Marks)

Module-5

- 9 a. Explain series and feedback compensation of a system with a diagram. (08 Marks)
- b. Explain lag compensator and lead compensator with a diagram. (08 Marks)

OR

- 10 a. Explain in brief controllability and observability. (10 Marks)
- b. Using Kalman's test determine whether the system represented by following state matrix is controllable or not.

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -1 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u \quad \text{and} \quad C = [1 \quad 1] x. \quad (06 \text{ Marks})$$
